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### COMPRESSED VIDEO EDITING

AUTHORING/EDITING 130



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### (57) Abstract

Techniques for detecting moving video objects in a compressed digital bitstream (111) and for tools for editing compressed video are disclosed. Video objects (117) are detected and indexed by analyzing a compressed bitstream to locate scene cuts (112), estimating operating parameters for a camera which initially viewed the video (114), and detecting one or more moving video objects represented in the compressed bitstream by applying global motion compensation which account for the estimated operating parameters. Tools are provided for permitting dissolve, masking, freeze frame, slow and variable speed playback, and strobe motion special effects to compressed video. The tools may be implemented in a system for editing (130) compressed video information over a distributed network.

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### Secription

Methods and Architecture for Indexing and Editing Compressed Video Over the World Wide Web

### Notice of Government Rights

The U.S. Government has certain rights in this invention pursuant to the terms of the National Science Foundation CAREER award IRI-9501266.

### Background of the Invention

Field of the invention.

The present invention relates to techniques for editing and parsing compressed digital information, and more specifically, to editing and parsing visual information in the compressed domain.

# . Description of the related art.

Syruth the increasing use of local area, wide area and global networks to spread information, digital video has become an essential component of many new media applications. The inclusion of video in an application often gives the application not only increased functional utility, but also an aesthetic appeal that cannot be obtained by text or audio information alone. However, while digital video greatly increases our ability to share information, it demands special technical support in processing, communication, and storage.

In order to reduce bandwidth requirements to manageable levels, video information is generally transmitted between systems in the digital environment the form of compressed bitstreams that are in a standard format, e.g., Motion JPEG, MPEG-1, MPEG-2, H.261 or H.263. In these compressed formats, the Discrete Cosine Transform ("DCT") is utilized in order to transform NxN blocks of pixel data, where n typically is set to eight, into the DCT domain where quantization is more readily performed. Run-length encoding and entropy coding (i.e., Huffman coding or arithmetic coding) are applied to the quantized bitstream

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to produce a compressed bitstream which has a significantly reduced bit rate than the original uncompressed source signal. The process is assisted by additional side information, in the form of motion vectors, which are used to construct frame or field-based predictions from neighboring frames or fields by taking into account the inter-frame or inter-field motion that is typically present.

In order to be usable by a receiving system, such coded bitstreams must be both parsed and decoded. For example, in the case of an MPEG-2 encoded bitstream, the bitstream must be parsed into slices and macroblocks before the information contained in the bitstream is usable by an MPEG-2 decoder. Parsed

bitstream information may be used directly by an MPEG-2 decoder to reconstruct the original visual information, or may be subjected to further processing.
In the case of compressed digital video, further processing of video information can occur either in the normal, uncompressed domain or in the compressed domain. Indeed, there have been numerous attempts by others in the field to realize useful techniques for indexing and manipulating digital video

information in both the uncompressed and compressed domains.

For example, in the article by S.W. Smoliar et al., "Content-Based Video Indexing and Retrieval," IEEE Multimedia, summer 1994, pp. 62-72, a color histogram comparison technique is proposed to detect scene cuts in the spatial (uncompressed) domain. In the article by B. Shahraray, "Scene Change Detection and Content-Based Sampling of Video Sequences," SPIE Conf. Digital Image Compression: Algorithms and Technologies 1995, Vol. 2419, a block-based match and motion estimation algorithm is presented.

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For compressed video information, the article by F. Arman et al., "Image Processing on Compressed Data for Large Video Databases," Proceedings of ACM Multimedia '93, June 1993, pp. 267-272, proposes a technique for detecting scene cuts in JPEG compressed images by comparing the DCT coefficients of selected blocks from each frame. Likewise, the article by J. Meng et al., "Scene Change Detection in a MPEG Compressed Video Sequence," IS&T/SPIE Symposium

Proceedings, Vol. 2419, Feb. 1995, San Jose, California, provides a methodology

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for the detection of direct scene cuts based on the distribution of motion vectors,

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and a technique for the location of transitional scene cuts based on DCT DC coefficients. Algorithms disclosed in the article by M.M. Yeung, et al. "Video Browsing using Clustering and Scene Transitions on Compressed Sequences," IS&T/SPIE Symposium Proceedings, Feb. 1995, San Jose, California. Vol. 2417,

pp. 399-413, enable the browsing of video shots after scene cuts are located.

However, the Smoliar et al., Shahraray, and Arman et al. references are limited to scene change detection, and the Meng et al. and Yeung et al. references do not provide any functions for editing compressed video.

Others in the field have attempted to address problems associated with

camera operation and moving objects in a video sequence. For example, in the
spatial domain, H.S. Sawhney, et al., "Model-Based 2D & 3D Dominant Motion
Estimation for Mosaicking and Video Representation," Proc. Fifth Int'l conf.
Computer Vision, Los Alamitos, CA., 1995, pp. 583-390, proposes to find

parameters of an affine matrix and to construct a mosaic image from a sequence of video images. In similar vain, the work by A. Nagasaka et al., "Automatic Video Indexing and Full-Video Search for Object Appearances," in E. Knuth and L. M. Wegner, editors, Video Database Systems, II, Elsevier Science Publishers B.V., North-Holland, 1992, pp. 113 - 127, proposes searching for object appearances and using them in a video indexing technique.

In the compressed domain, the detection of certain camera operations, e.g., zoom and pan, based on motion vectors have been proposed in both A. Akutsu et al., "Video Indexing Using Motion Vectors," SPIE Visual Communications and Image Processing 1992, Vol. 1818, pp. 1522-1530, and Y.T. Tse et al., "Global Zoom/Pan Estimation and Compensation For Video Compression" Proceedings of

125 ICASSP 1991, pp.2725-2728. In these proposed techniques, simple three parameter models are employed which require two assumptions, i.e., that camera panning is slow and focal length is long. However, such restrictions make the algorithms not suitable for general video processing.

There have also been attempts to develop techniques aimed specifically at digital video indexing. For example, in the aforementioned Smoliar et al. article, the authors propose using finite state models in order to parse and retrieve specific

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domain video, such as news video. Likewise, in A. Hampapur, et al., "Feature Based Digital Video Indexing," IFIP2.6 Visual Database Systems, III, Switzerland, March, 95, a feature based video indexing scheme using low level machine derivable indices to map into the set of application specific video indices is

presented.

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One attempt to enable users to manilupate image and video information was proposed by J. Swartz, et al., "A Resolution Independent Video Language," Proceedings of ACM Multimedia '95, pp. 179-188, as a resolution independent video language (Rivl). However, although Rivl uses group of pictures (GOPs)

- 10 level direct copying whenever possible for "cut and paste" operations on MPEG video, it does not use operations in the compressed domain at frame and macroblock levels for special effects editing. Instead, most video effects in Rivl are done by decoding each frame into the pixel domain and then applying image library routines.
- The techniques proposed by Swartz et al. and others which rely on performing some or all video data manipulation functions in the uncompressed domain do not provide a useful, truly comprehensive technique for indexing and manipulating digital video. As explained in S.-F. Chang, "Compressed-Domain Techniques for Image/Video Indexing and Manipulation," IEEE Intern. Conf. on Image Processing, ICIP 95, Special Session on Digital Image/Video Libraries and Video-on-demand, Oct. 1995, Washington DC, the disclosure of which is incorporated by reference herein, the compressed-domain approach offers several powerful benefits.
- First, implementation of the same manipulation algorithms in the compressed domain is much cheaper than that in the uncompressed domain because the data rate is highly reduced in the compressed domain (e.g., a typical 20:1 to 50:1 compression ratio for MPEG). Second, given most existing images and videos stored in the compressed form, specific manipulation algorithms can be applied to the compressed streams without full decoding of the compressed
- applied to the compressed streams without full decoding of the configuration of video are images/videos. In addition, because that full decoding and re-encoding of video are not necessary, manipulating video in the compressed domain avoids the extra

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quality degradation inherent in the reencoding process. Thus, as further explained in the article by the present inventors, J. Meng and S.-F. Chang, "Tools for Compressed-Domain Video Indexing and Editing," SPIE Conference on Storage and Retrieval for Image and Video Database, Vol. 2670, San Jose, California, Feb.

- 1996, the disclosure of which is incorporated by reference herein, for MPEG compressed video editing, speed performance can be improved by more than 60 times and the video quality can be improved by about 3-4 dB if a compressed-domain approach is used rather than a traditional decode-edit-reencode
- video must meet two requirements. First, the technique must provide for key content browsing and searching, in order to permit users to efficiently browse through or search for key content of the video without full decoding and viewing the entire video stream. In this connection, "key content" refers to key frames in video sequences, prominent video objects and their associated visual features (motion, shape, color, and trajectory), or special reconstructed video models for representing video content in a video scene. Second, the technique must allow for video editing directly in the compressed domain to allow users to manipulate an specific object of interest in the video stream without having to fully decode the

Unfortunately, none of the prior art techniques available at present are able to meet these requirements. Thus, the prior art techniques fail to permit users who want to manipulate compressed digital video information with the necessary tools to extract a rich set of visual features associated with visual scenes and individual objects directly from compressed video so as not only to enable content based query searches, but also to allow for integration with domain knowledge for derivation of higher-level semantics.

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arbitrary segment from an existing video stream to produce a new video stream

which conforms to the valid compression format.

video. For example, the technique should permit a user to cut and paste any

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### Summary of the Invention

An object of the present invention is to provide comprehensive techniques for indexing and manipulating digital video in the compressed domain.

Another object of the present invention is to provide techniques for key content browsing and searching of compressed digital video without decoding and viewing the entire video stream.

A further object of the present invention is to provide techniques which allow for video editing directly in the compressed domain

A still further object of the present invention is to provide tools that permit

10 users who want to manipulate compressed digital video information to extract a

rich set of visual features associated with visual scenes and individual objects

directly from compressed video.

Yet another object of this invention is to provide an architecture which permits users to manipulate compressed video information over a distributed network, such as the Internet.

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In order to meet these and other objects which will become apparent with reference to further disclosure set forth below, the present invention provides a method for detecting moving video objects in a compressed digital bitstream which represents a sequence of fields or frames of video information for one or more

- previously captured scenes of video. The described method advantageously provides for analyzing a compressed bistream to locate scene cuts so that at least one sequence of fields or frames of video information which represents a single video scene is determined. The method also provides for estimating one or more operating parameters of a camera which initially captured the video scene, by
- analyzing a portion of the compressed bitstream which corresponds to the video scene, and for detecting one or more moving video objects represented in the compressed bitstream by applying global motion compensation with the estimated camera operating parameters.
- In a preferred process, the compressed bitstream is a bitstream 30 compressed in accordance with the MPEG-1, MPEG-2, H261, or H263 video standard. In this preferred embodiment, analyzing can beneficially be

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accomplished by parsing the compressed bitstream into blocks of video information and associated motion vector information for each field or frame of video information which comprises the determined sequence of fields or frames of video information representative of said single scene, performing inverse motion compensation on each of the parsed blocks of video information to derive discrete cosign transform coefficients for each of the parsed blocks of video information, counting the motion vector information associated with each of the parsed blocks of video information, and determining from the counted motion vector information and discrete cosign transform coefficient information whether one of the scene cuts

has occurred.

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In an alternative embodiment, analyzing is performed by parsing the compressed bitstream into blocks of video information and associated motion vector information for each field or frame of video information which comprises the determined sequence of fields or frames of video information representative of the scene, and estimating is executed by approximating any zoom and any pan of the camera by determining a multi-parameter transform model applied to the parsed motion vector information. In an especially preferred process, the frame difference due to camera pan and zoom motion may be modeled by a six-parameter affine transform which represents the global motion information representative of the zoom and pan of the camera.

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The detecting step advantageously provides for computing local object motion for one or more moving video objects based on the global motion information and on one or more motion vectors which correspond to the one or more moving video objects. In addition, thresholding and morphological operations are preferably applied to the determined local object motion values to eliminate any erroneously sensed moving objects. Further, border points of the detected moving objects are determined to generate a bounding box for the detected moving object.

The present invention also provides for an apparatus for detecting moving video objects in a compressed digital bitstream which represents a sequence of fields or frames of video information for one or more previously captured scenes

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of video. Usefully, the apparatus includes means for analyzing the compressed bistream to locate scene cuts therein and to determine at least one sequence of fields or frames of video information which represents a single video scene, means for estimating one or more operating parameters for a camera which initially viewed the video scene by analyzing a portion of the compressed bitstream which corresponds to the video scene, and means for detecting one or more moving video objects represented in the compressed bitstream by applying global motion compensation to the estimated operating parameters.

A different aspect of the present invention provides techniques for dissolving an incoming scene of video information which comprises a sequence of fields or frame of compressed video information to an outgoing scene of video information which comprises a sequence of fields or frame of compressed video information. This technique advantageously provides for applying DCT domain motion compensation to obtain DCT coefficients for all blocks of video information which make up a last frame of the outgoing video scene and the first frame of the incoming video scene, and for creating a frame in the dissolve region

In an especially preferred arrangement, an initial value for a weighting function is selected prior to the creation of a first frame in the dissolve region and is used in the creation of the first frame in the dissolve region. The weighting value is then incremented, and a second dissolve frame from the DCT coefficients is generated.

frame from the DCT coefficients of the last outgoing frame and the first incoming

frame.

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In yet another aspect of the present invention, a technique for masking a compressed frame of digital video information is provided. The technique first determines whether the frame to be masked is intra-coded, predictive-coded or bidirectionally predictive-coded. If the frame is intra-coded, the technique provides for extracting DCT coefficients for all blocks within the frame, examining a block, to determine where in the frame the block is located, setting DCT coefficients for the block to zero if the block is outside the mask region, and applying a DCT

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cropping algorithm to the DCT coefficients if the block is on the boundary of the

mask region.

If the frame is predictive-coded or bi-directionally predictive-coded, the technique provides for examining motion vectors associated with block, to determine whether they point to blocks outside or on the mask region, and reencoding the block if a motion vector points to blocks outside the boundary, or on, the mask region.

In still another aspect of the present invention, a technique for generating a frozen frame of video information from a sequence of frames of compressed video information is provided. The technique attractively provides for selecting a frame of compressed video information to be frozen, determining whether the frame to be frozen is intra-coded, predictive-coded or bi-directionally predictive-coded, and if the frame is not intra-coded, converting it to become intra-coded, creating duplicate predictive-coded frames, and arranging the intra-coded frame and the duplicate predictive-coded frames into a sequence of compressed frames of video information.

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In yet a further aspect of the present invention, a system for editing compressed video information over a distributed network is provided. The system includes a client computer, a network link for permitting said client computer to search for and locate compressed video information on said distributed network, and tools for editing a compressed bitstream of video information over the distributed network.

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The accompanying drawings, which are incorporated and constitute part of this disclosure, illustrate a preferred embodiment of the invention and serve to explain the principles of the invention.

## Brief Description of the Drawings

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Fig. 1 illustrates a system in accordance with one aspect of the present

Fig. 2. is a flowchart which illustrates how a scene cut is detected in

accordance with one aspect of the present invention;

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Fig. 3. is a flowchart which illustrates how camera parameters are estimated in accordance with one aspect of the present invention;

Fig. 4 is a vector diagram which serves to explain global and local motion;

Fig. 5 depicts an exemplary frame of compressed video information and

motion vectors for the frame;

Fig. 6 is a flowchart which illustrates global motion compensation in

accordance with one aspect of the present invention;

Fig. 7 depicts prior art editing of compressed video bistreams;

Fig. 8a depicts the dissolve effect; Fig 8(b) is a flowchart which illustrates

the dissolve effect;

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Fig. 9a depicts masking; Fig 9(b) is a flowchart which illustrates masking;

Fig. 10 is a flowchart which illustrates the freezeframe effect;

Fig. 11 depicts two alternative techniques for the slow motion effect;

Fig. 12 is a system diagram of a distributed network in accordance with one

aspect of the present invention; and

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 Fig. 13 depicts exemplarily techniques which may be executed in the distributed network illustrated in Fig. 12.

# Description of the Preferred Embodiments

Referring to Fig. 1, an exemplary embodiment of our invention which permits a user to edit and parse visual information in the compressed domain is provided. The architecture of the system 100 is broadly arranged into three functional modules, a parsing module 110, a visualization module 120, and an authoring and editing module 130.

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In the parsing module, an incoming bitstream of compressed video

information 111 which may be, for example, an MPEG-2 compressed bitstream is examined for scene cuts 112 and broken into shot segments, where each segment includes one or more fields or frames of compressed video information. In an MPEG-2 bitstream, the shot segments will be made of three types of fields or frames, i.e., Intra-coded ("I") fields which are coded independently and entirely without reference to other fields, Predictive-coded ("P") fields which are coded

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"point" to blocks of video information in a preceding or succeeding field or frame directionally predictive-coded ("B") fields which are coded with reference to the nearest preceding and/or future I or P fields in the sequence. The bistream will also include associated motion vector information for the P and B fields which with reference to temporally preceding I or P fields in the sequence, and Biwhich are needed to reconstruct the compressed field or frame of video

indexing the compressed video information. The individual shot segments are next captured the video information which is being analyzed. Histogram 115 is used to detect the pan of the camera. Based on the derived operating parameters, moving objects 117 within the compressed video information 116 are detected and shape analyzed 113 in order to derive camera operation parameters. In Figure 1, the The parsing module compiles a list of scene cuts which are useful for vector field 114 is representative of the pan of the camera which originally and trajectory features for such moving objects are extracted.

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to index and retrieve key frames or video objects based on their visual features and image and Video Databases IV, IS&T/SPIE's Electronic Images; Science & Tech. 96, Vol 2670 (1996). A content-based image query system 126 may then be used which represent each video shot. The key frames 121 are placed in a hierarchical arrangement 125 so that they may be readily browsed with a hierarchical video In the visualization module 120, the complied list of scene cuts and the Methods for Video Browsing and Annotation," Storage and Retrieval for Still derived camera zoom and pan information are used to extract key frames 121 scene browser, such as the browser described in D. Zhong et al., "Clustering

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new video segments, but also to add special effects to such video segments, such as In the authoring and editing module 130, software tools are provided to not only enable a user to cut and past arbitrary compressed video segments to form dissolve, key, masking and motion effects.

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The parsing module 110 is explained in further detail with reference to the figures 2 and 3. Although the preferred steps executed e.g. on a computer 131 to

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locate scene cuts in a compressed bitstream are fully disclosed in the above referenced article by Meng et al., the disclosure of which is incorporated by reference herein, that technique is now decribed with reference to figure 2.

an arrangement of NxN blocks of video information that are broadly organized into slices which represent contigous sequences of macroblocks of video information in raster scan order. The NxN blocks of video information are preferably 8x8 blocks. information and one block of chrominance information, and further organized into The bitstream also represents associated motion vector information and prediction An MPEG-1 or MPEG-2 compressed bitstream 201 that is received by the parsing module 110 is first subjected to parsing 210. Such a bitstream represents error difference information which are needed to reconstruct original blocks of macroblocks, where each macroblock is defined by four blocks of luminance S 2

block level by parsing techniques known to those skilled in the art 211. The parsed blocks of video information are still in compressed format and are thus represented In the parsing stage 210, the bitstream, is parsed down to the fundamental by Direct Cosign Trasform ("DCT") coefficients which have been quantized, Zig-Zag run-length encoded and variable length coded, as those skilled in the art will appreciate.

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information which belong to P and B frames are then subjected to inverse motion olocks of video information in the B and P frames. In this step 220, only the first In the inverse motion compensation stage 220, the parsed blocks of video compensation 220 by using the associated motion vector information to locate reference blocks of video information and reconstruct the DCT coefficients of

(the "DC") DCT coefficients are used. Motion vectors associated with the B and P In the Statistical Stage 230, three ratios, i.e., the number of intra-coded frames are counted 222 for each frame in the sequence. 23

forward motion vectors to the number of backward motion vectors, are calculated 231 in order to detecting direct scene cuts in P, B, and I frames, respectively. In motion vectors to the number of forward motion vectors, and the number of 30

macroblocks to the number of forward motion vectors, the number of backward

this stage, the fact that most video shots of compressed MPEG video are formed by consecutive P, I and B frames that have a high degree of temporal correlation is taken advantage of. For P and B frames, this correlation is characterized by the ratio of the number of backward motion vectors, or intracoded macroblocks, to the number of forward motion vectors. For example, when a direct scene cut occurs

Also in the statistical stage 230 the variance of the DCT DC coefficients of Luminance in the I, P and B frames is determined 232. As those skilled in the art will appreciate.

on a P-frame, most macroblocks will be intracoded (i.e., no interframe prediction).

Next, in the detection stage 240, the ratios calculated in 231 are compared to local adaptive thresholds in order to detect the peak values 241. For P frames, the ratio of the number of intra-coded macroblocks to the number of forward motion vectors is examined. For B frames, the ratio of the number of backward motion vectors to the number of forward motion vectors is examined.

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- also in the detection stage 240, the variance of DCT DC coefficients calculated for I and P frames in 232 is used in two ways. For I frames, this variance information is used together with the ratio of the number of forward motion vectors to the number of backward motion vectors determined in 231 in order to detect candidate scene changes 242. If the ratio is above a predetermined threshold, the frame is marked as containing a suspected scene cut. If the variable information is much different than was the variance information for the immediately preceding I frame, a suspected scene cut is likewise detectable. The variance information is also used directly to detect dissolve regions, i.e. regions where one scene is fading out and a second is fading in 243 by examining the parabolic curve of the variance information.
- In the decision stage 250, duplicate detections of scene cuts are eliminated 251 before list of scenes 252 is determined. In addition, if a suspected scene change occurs within a time threshold T rejection of a previously detected scene change, no scene change is recorded.
- 30 With scene cuts detected, the bitstream is broken into scenes or "shots" which represent different sets of visual information that may be of interest to a

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user. The next block of our parsing module 110, camera operating estimation 113, examines the individual shots for recognizable information which is highly useful in indexing the different shots which have been parsed.

In particular, certain low level visual features such as camera zoom and pan, and the presence of moving visual objects are useful information for video indexing. Camera zoom and pan, which give the global motion of the shot being analyzed, can be estimated with a 6-parameter affine transform model by using the actual motion vectors from the MPEG compressed stream.

The motion vectors in MPEG are usually generated by block matching:

10 finding a block in the reference frame so that the mean square error of prediction is minimized. Although the motion vectors do not represent the true optical flow, it is still good in most cases to estimate the camera parameters in sequences that do not contain large dark or uniform regions.

When the distance between the object or background and the camera is

15 large, a 6 parameter affine transform can be used to describe the global motion of

$$\begin{bmatrix} u \\ v \end{bmatrix} = \begin{bmatrix} 1 & x & y & 0 & 0 \\ 0 & 0 & 0 & 1 & x & y \end{bmatrix} \cdot \begin{bmatrix} a_1 & a_2 & a_3 & a_4 & a_5 & a_6 \end{bmatrix}^T \tag{1}$$

where (x, y) is the coordinate of a macroblock in the current frame,  $[u \ v]^T$  is the motion vector associated with that macroblock, and  $[a_1 \ a_2 \ a_3 \ a_4 \ a_5]^T$  is the affine transform vector. In order to simplify the mathematics, the following variables can be defined:

U for [u, v]<sup>T</sup>

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X for 
$$\begin{bmatrix} 1 & y & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & x & y \end{bmatrix}$$
,

and  $\hat{\mathbf{a}}$  for  $[\mathbf{a}_1 \ \mathbf{a}_2 \ \mathbf{a}_3 \ \mathbf{a}_4 \ \mathbf{a}_5 \ \mathbf{a}_6]^T$ .

Given the motion vector for each macroblock, a global parameter can be determined using Least Squares ("LS") estimation by finding a set of parameters to a minimize the error between the motion vectors estimated in (1) and the actual motion vectors obtained from the MPEG stream:

$$S(\vec{k}') = \sum_{X} \sum_{Y} \left[ (\vec{u}_{xy} - u_{xy})^2 + (\vec{v}_{xy} - v_{xy})^2 \right] \tag{2}$$

In equation (2),  $[0, \theta]^T$  is the estimated motion vector.  $\hat{a}$  is then solved for by setting the first derivative of S(a) to 0 to get:

$$\begin{bmatrix} N & A & B \\ A & C & E \end{bmatrix} \cdot \begin{bmatrix} a_1 \\ a_2 \\ a_3 \end{bmatrix} = \begin{bmatrix} U_1 \\ U_2 \end{bmatrix} \text{ and } \begin{bmatrix} N & A & B \\ A & C & E \end{bmatrix} \cdot \begin{bmatrix} a_4 \\ a_5 \\ B & E & D \end{bmatrix} \begin{bmatrix} V_1 \\ V_2 \\ A & C \end{bmatrix}$$
(3)

where,

$$N = \sum_{i} \sum_{j} 1, A = \sum_{i} \sum_{j} x, B = \sum_{i} \sum_{j} y,$$

$$C = \sum_{i} \sum_{j} x^{2}, D = \sum_{i} \sum_{j} y^{2}, E = \sum_{i} \sum_{j} x \cdot y,$$

$$U_{1} = \sum_{i} \sum_{j} u_{1j}, U_{2} = \sum_{i} \sum_{j} u_{1j}, x, U_{3} = \sum_{i} \sum_{j} u_{1j}, y,$$

$$V_{1} = \sum_{i} \sum_{j} v_{1j}, v_{2} = \sum_{i} \sum_{j} v_{1j}, x, v_{3} = \sum_{i} \sum_{j} v_{1j}, y.$$

vectors survive after the nonlinear noise reduction process. (For example, median filter.) This process is used to eliminate obvious noise in the motion vector field All summations are computed over all valid macroblocks whose motion After the first LS estimation, motion vectors that have large distance from the estimated ones are filtered out before a second LS estimation. The estimation process is preferably iterated several times to refine the accuracy.

intermediate variables N, A, B, C, D, and E are interactively calculated using the x Referring to figure 3, the foregoing process to determine a global motion analyzed 320. Next, intermediate transform parameters u1, u2, u3, v3, v3, v3 are parameter is illustrated in flow diagram 300. In step 310, each motion vector associated with the B and P frames contained in the shot are decoded. The and y coordinates for each macroblock in the current frame of video being 2 2

calculated using the decoded motion vectors and the x and y coordinates for such

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macroblocks 330. Finally, the vector a is solved for by solving for the matrix

After the global camera parameters à are found, object motion can be inverse operation 340.

reference frame with motion vector U, then  $U+M=X\cdot\hat{a}$  . Thus, the motion of object located at (x, y) in the current frame moves from  $(x_0, y_0)$  to  $(x_1, y_1)$  in the extracted by applying global motion compensation. Referring to figure 4, if an the local object can be recovered from its associated motion vectors as follows:

$$A = X \cdot \hat{\mathbf{a}} - U \tag{4}$$

motion vectors of the foreground moving objects, GMC reveals the local motion of background. In figure 5(a), the original motion vectors for an exemplary frame of compressed video is illustrated. In figure 5(b), the vector map for the exemplary This is referred to as the global motion compensation ("GMC"). With frame is shown after GMC has been applied. As illustrated in figure 5(b), for motion vectors of the background, GMC gives mostly zero values, while for reference to figure 5, a moving ballerina is shown against a largely stagnant 2 15

performing simple morphological operations to delete small false objects and to fill noisy spots. For example, in figure 5(c) there is shown an extracted moving object. The moving objects themselves can be detected by comparing the magnitude of the local motion to a predetermined threshold value and by

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compensation algorithm, as disclosed in U.S. Patent No. 5,408,274 to Chang et al., The DCT coefficients of the moving object are extracted from the compressed video information to provide for later querying of the object. Extraction of the DCT coefficient is done by the DCT domain motion

the disclosure of which is incorporated by reference herein. The outermost points of the extracted object are used to form a bounding box, as illustrated in figure 2

Again referring to figure 1, in the visualization module 120, the location and size of each extracted bounding box is saved in a database 126 for later

browsing and indexing by a user. Likewise, visual features of extracted objects, such as color, textures, and shape, are used to provide content-based visual querying 127 of these and associated video scenes.

compensated motion vector is compared to a predetermined threshold value 620 in order to eliminate non-moving parts of the frame from further consideration. Next, for blocks of information which still have non-zero motion vectors, the number of now be described with reference to the flow diagram 600 of figure 6. First, GMC associated blocks are compared to a predetermined minimum threshold value 640 The extraction of moving video objects from a compressed bitstream will contiguous blocks are counted 630. For each contiguous area, the number of is applied to the present frame of video 610. Second, each globally motion

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all blocks within the border. In this way, the important moving video object can be database 126, for later use 650, together with corresponding DCT coefficients for n order to eliminate false small objects from being detected. Finally, the border points for the remaining objects are identified and saved in a database, e.g. extracted and indexed for later viewing by a user. 12

video is directed to permitting a user to cut a first segment of video 710 from a first compressed digital video will now be described. In general, editing of compressed video sequence 720 and a second segment of video 730 from a second sequence of J. Meng et al., "Tools for Compressed-Domain Vide Indexing and Editing," SPIE Conf. on Storage and Retrieval for Image and Video Database, Vol. 2670 (1996), have been described in the art, including in the article by the present inventors, video 740 to form a new bitstream of video information 750. Such techniques With reference to figure 7, useful techniques for directly editing the disclosure of which is incorporated by reference herein.

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advanced visual effects can be created in the compressed domain. For I frames, the basic compression component is the Discrete Cosine Transform (DCT), which can In addition to the basic editing function "cut and paste", several more be written in the following form:

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F(u,v) = DCT(f(x,y))

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Given the DCT; linear operations such as intensity addition and scaling can performed in accordance with equations (6) and (7):

$$DCT(f_1(x,y) + f_2(x,y)) = F_1(u,v) + F_2(u,v)$$
(6)  
$$DCT(\alpha:f(x,y)) = \alpha \cdot F(u,v)$$
(7)

$$DCT(\alpha \cdot f(x,y)) = \alpha \cdot F(u,v)$$
 (7)

output video Y can be obtained by linear matrix operations of the input DCT, P., as Algorithms for other operations such as spatial scaling, translation, and filtering in DCT domain are well known in the art. Generally, the DCT of the

$$Y = \sum W_i \cdot P_i \cdot H_i \tag{8}$$

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the above techniques can be readily applied. An alternative approach is to keep the effects which can be created in the compressed domain - dissolve, masking, freeze B or P structure (i.e., the DCT coefficients of residual errors and motion vectors) where H<sub>i</sub> and W<sub>i</sub> are special filter coefficient matrices in the DCT domain. For can be used to convert B and P frames to intraframe DCT coefficients, on which functions can be implemented in two ways. First, transform-domain techniques and develop algorithms directly utilizing these data. Several advanced visual motion compensated B and P frames, the compressed-domain manipulation frame, variable speed, and strobe motion - are now particularly described.

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Chang et al. patent describes a technique which uses DCT domain inverse motion illustrated in figure 8(a), dissolve refers to the technique where an outgoing video scene 801 is faded out while an incoming video scene 802 is faded in. In order to for each block of compressed video in the last frame of the outgoing video scene, and the DCT coefficients for each block of compressed video in the first frame of perform a dissolve on two different scenes of video, the actual DCT coefficients the incoming video scend, must be extracted. One technique for extracting such DCT coefficients is described in the above-mentioned Chang et al. patent. The One of the most important tools used in film editing is dissolve. As 20 22

compensation to obtain the DCT coefficients for all blocks of video information which make up the needed frames of video.

When there is no or little motion in the two videos scenes, the dissolve effects can be approximated by the linear combination of the two video scenes  $F_1$  and  $F_2$ :

$$F(u,v,t) = \alpha(t) \cdot F_1(u,v,t_1) + (1-\alpha(t)) \cdot F_2(u,v,t_2)$$
 (9)

v and v are coordinates within a frame, t is the frame index value which may range from 1 to N, n being the total number of frames in the dissolved region, and  $\alpha(t)$  is a weighing function that is variable from 100% to 0%,  $F_1$  is the composite of the derived DCT coefficients for all blocks which make up the last frame of the outgoing video scene and  $F_2$  is the composite of the derived DCT coefficients for all blocks which make up the first frame of the incoming video scene. The resulting effect is a dissolve transition from a particular frozen frame of the outgoing video scene to another frozen frame of the incoming video scene.

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Thus, to smooth out the dissolve where one or both of the dissolving scenes contain moving video objects, it is desirable to re-encode several dissolving frames over a transitional period t<sub>1</sub> - t<sub>2</sub>. The reader is referred to the Appendix of this patent document for our preferred source code for implementing a dissolve.

Referring to figure 8(b), a method for dissolving an incoming scene and an outgoing scene of video is now described by way of a flowchart 800. In step 810, DCT domain motion compensation is used to obtain the DCT coefficients for all blocks of video information which make up the last frame of an outgoing video scene F<sub>1</sub>. In step 820, DCT domain motion compensation is used to obtain the DCT coefficients for all blocks of video information which make up the first frame of an incoming video scene F<sub>2</sub>. In step 830, the initial value for the weighing function, α(t), is chosen. In step 840, equation 9 is applied to create a first frame in the dissolve region. The value of t is then incremented until a final value n is obtained 850. The process 830-850 is repeated to create all dissolve frames for the duration t = 1 to n.

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A second important tool used in film editing is masking. As illustrated in figure 9(a), the film effect of masking video refers to transforming an original video scene having e.g. a 4.3 aspect ratio to different aspect ratios such as 1:1.66, 1:1.85, 1:2.35, or 16:9. Masking can also be used to crop part of the frame region to a different frame size. For I frames, the DCT coefficients for blocks outside of the desirted region are set to 0, and the coefficients for blocks that lie on the masking boundaries can recalculated using a simplified DCT cropping algorithm:

$$DCT(B) = DCT(H) \cdot DCT(A), \text{ where } H = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$$
 (10)

10 where A is an original block located on the boundary, B is the new masked block, and I<sub>b</sub> is the identity matrix with size h x h, as shown in figure 9a.

For P and B frames, only macroblocks with motion vectors pointing outside of the masking region need to be re-encoded. Macroblocks with motion vectors pointing inside do not need any modification. Efficient algorithms for reencoding macroblocks are well known in the art and are described in, for example, the above-referenced Chang et al. patent.

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Referring to figure 9(b), a method for performing masking is now described. In step 910, the frame to be masked is examined in order to determine whether it is an I, P or B frame. If the frame is an I frame 911, all DCT

coefficients for all blocks within the frame are extracted 920. Block, is examined 930 to determine where in the frame it is located. If the block is inside the mask region 931, the DCT coefficients for the block are unchanged 941. If the block is outside the make region 932, the DCT coefficients for the block are set to zero 942. If the block is on the boundary of the masked region 933, the DCT cropping algorithm, i.e., equation 10, is applied 943. The block index n is incremented 950 and the process repeated 930-950 until all blocks have been examined.

If, however, the frame to be masked is either a P or B frame 920, motion vectors associated with block, are examined 960 to determine whether they point to blocks outside or on the mask region 970. If a motion vector points to blocks

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index n is incremented 990 and the process repeated 960-990 until all blocks have been examined.

freeze effect is usually longer than 1 second, simply repeating duplicate frames is not desirable if interactive playback (e.g. random search) is desired. Instead, the A third important tool used in film editing is the freeze effect. Since the film effect of freeze frame requires the use of periodic I frames.

frame is a P or B frame, it should be converted to an I frame. In order to convert a P or B frame into an I frame, every block of video information for the frame that Thus, in order to ensure interactive playback capabilities, if the frozen

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nas an associated motion vector is converted into a pure array of DCT coefficients, without motion vector information. The above-mentioned DCT domain motion intracoded blocks. Thereafter, the group of pictures which represent the frozen compensation algorithm described in the Chang et al. patent is advantageously used to effect such conversion. The converted blocks can be referred to as 2 15

residue error). Duplicate P frames can easily be created independently and inserted after I or P frames, as those familiar with digital compression techniques will easily frame are filled with duplicated P frames, with all macroblocks in the duplicated P frames being to Motion Compensation Not Coded (i.e., 0 motion vector, and 0 understand.

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frame effect. In step 1020, the frame is examined in order to determine whether it frame 1030. Finally, original 1022 or converted 1030 I frames are then used as to is an I, P or B frame. If the frame is not an I frame 1021, it is converted into an I create duplicate P frames 1040. Periodical I frames can be inserted to increase user-defined frame of compressed video information is selected for the freeze-A method for generating a frozen frame of video information is now described with reference to flowchart 1000 in figure 10. In step 1010, a nteractivity, and to maintain a compatible bitrate.

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Faster than normal playback, e.g., fast forward, is simply realized by dropping B, A fourth important tool used in film editing is variable speed playback. P, and then I frames according to the variable speed desired 8

insert duplicate B frames (B') whenever an original B frame appears. Duplicate B transmitted 4 frames earlier. This limitation makes this approach suitable for slow playback up to about 1/3 normal frame rate. This will require an increased decoder With respect to slow motion, depending on the slow motion rate, there are illustrative sequence of frames shown in figure 11, the reference frame Io must be frames are frames which copy all DCT coefficient, and associated motion vectors increased by a factor equal to the inverse of the motion rate. For example, in the two possible approaches. With reference to figure 11, one approach is to simply approach. However, this approach has a drawback since the I/P frame delay is from previous B frame. There is no decoding or re-encoding involved in this

domain techniques described above, and duplicated P frames are inserted between I In approach 2, original P/B frames are converted to I frames using the DCT frames, as in the case with freeze frame. This approach reduces frame delay, although requiring extra DCT domain manipulations.

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Another interesting tool used in film editing is the special effect of strobe playback. Strobe motion is effected by dropping original B and/or P frames and motion, which is simply a combination of freeze frame and variable speed inserting duplicated P frames.

distant servers 1220, 1230, 1240 and several clients 1250, 1260. From their client workstations, users are empowered to browse and edit compressed vide images in Referring to figure 12, a system for enabling distributed clients to browse and manipulate digital video by way of a distant server or host computer is now described. A master server 1210 or a group of distributed servers is linked to the manner described above. 2 52

1310 to collect video content, and as a content analyzer 1320 to analyze the visual functions performed by the parsing module 110 described above. The server 1210 Moving to figure 13, the master server 1210 acts as the content aggregator described above, for rendering basic editing functions and various special effects. also provides an editing engine 1340 with basic editing tools, such as the tools content for efficient indexing 1330. Thus, the server 1210 may accept the 8

heterogeneous networks with interoperable interfaces, such as JAVA or MPEG Distributed clients 1250, 1260 access the video archives of the server through MSDL manipulation tools.

1230, 1240 that have video search engines which search for image and video over a network, e.g., the World Wide Web. Once a video file is found on any other hosts or online content providers, it will be downloaded and preprocessed by the video server 1210 to extract "keyframes," i.e., frames 121 stored in the above described The video server 1210 can be linked with other distributed servers 1220, visualization module 120, and associated visual features such as camera motion, moving objects, color, texture, and temporal features. The Universal Resource video server 1210. This client-server model empowers clients 1250, 1260 with Location ("URL") of the video and the extracted features will be stored on the much richer resources beyond that provided by the client's local system.

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view. A sequential view arranges the video shots according to the sequential time order; a feature-based view clusters video shots with similar visual features to the same group; a story view presents video shots according to the story structures in the semantic level. For example, for news applications, the story model may use level editing 1390 using the above discussed editing tools. The clients may also submit their own videos which may be analyzed and indexed by the server 1210. viewing models, including sequential view, feature-based view, and story-based he anchorperson shot as the criterion for automatic segmentation of video into browse 1330 the keyframes hierarchically using any one of numerous different The client 1260 may open any video shot stored at the server 1210 and semantic-level stories. The client can also perform shot-level editing or frame 2

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video with desired special effects to be generated. Finally, when the client 1260 no second level, the client may send information to the server defining low-resolution can render only straight cuts at low resolution without any special effects. At the There are three broad levels of video rendering. At the first level, the client 1260 choose different levels of resolution for the video shots sent by the server 1210. To view or to further refine retrieved video shots, the client 1260 may onger wishes to perform editing, the master server 1210 will generate a 8 22

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distributed remote content servers 1220, 1230, 1240. In this way, the user is given full-resolution video with all the effects requested by the client from the highest quality source video which is located at either the master server 1210 or the the flexibility to tradeoff between quality and speed.

the original video. For I frames, DCT DC coefficients are obtained directly. For B from the full resolution video. The icon stream is an 8:1 down sampled version of sequence stored on a server, a low resolution icon stream video must be extracted coefficients. Finally, the extracted coefficients are converted into a smaller sized, and P frames, DCT domain inverse motion compensation is applied to the DCT In order to obtain a reduced resolution video sequence, for each video e.g., 8:2:1, I frame as those skilled in the art will appreciate. 2 S

while the above description was directed to indexing and editing digital vide which to devise numerous systems and methods which, although not explicitly shown or compensation. It will thus be appreciated that those skilled in the art will be able The foregoing merely illustrates the principles of the invention. Various equally applicable to other compressed bitstreams, e.g., Motion JPEG, H.261 or described herein, embody the principles of the invention and are thus within the modifications and alterations to the described embodiments will be apparent to hose skilled in the art in view of the inventors teachings herein. For example, has been compressed in accordance with the MPEG format, the foregoing is H.263, or any other algorithm based on transform coding and motion spirit and scope of the invention.

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newDCT[cc][j][k] = (short) CLAMP(-2048,(1-alpha)*tmpDCT[cc][j][k]
                                                                                                                                                                                                                                                                                                                                     blks = (coded_picture_width*coded_picture_height)>>6;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    /* use refoldDCT as reference frame for DPCM of P */
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            +alpha*refDCT[cc][j][k],2047);
                                                                                                                                                                                                                                                                                                                                                                                                 blks = (chrom_width*chrom_height)>>6;
                                                                                                                                               oldrefDCT[i] = auxDCT[i];
                                                                                                                                                                                                               newDCT[i]= auxDCT[i];
                                                           alpha=s/(double)duration;
                             for(s=1;s<=duration;s++) {
                                                                                                                                                                                                                                                                             for (cc=0; cc<3; cc++) {
                                                                                                                                                                                                                                                                                                                                                                                                                                  for (j=0; j<blks; j++) {
                                                                                                                                                                                                                                                                                                                                                                                                                                                               for (k=0; k<64; k++)
                                                                                                                    tmp[i] = oldrefDCT[i];
                                                                                                                                                                                  auxDCT[i] = tmp[i];
                                                                                       for (i=0; i<3; i++) {
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    putpictDCT(0);
                                                                                                                                                                                                                                                                                                           if (cc==0)
                                                                                                                                                                                                                                                                              2
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          20
                                                                                                                                                                                                                                                                                                                                                                                                                                     15
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          memcpy(unpDCT[cc], refDCT[cc], blks * sizeof(short [64]));
                                                                                                                                                                                                                                                                                                                                                                                                                                                                  blks = (coded_picture_width*coded_picture_height)>>6;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              blks = (chrom_width*chrom_height)>>6;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 /* first prediction is based on tmpDCT */
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     getDCTframe(ld->begin, GETDCT);
                                                                                                                                                                                                                                                                                                                                                                      /* copy the first DCT to tmpDCT */
                                                                                                                                                                                                                                                                                                                                          getDCTframe(ld->end, GETDCT);
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       ld->begin = roundtoP(ld->begin);
                                                                                                                                                                                                                                                                              Id->end = roundtoP(Id->end);
                                                                                                                                                                                                                                                                                                             do_cut(ld->begin, ld->end);
                              int do_dissolve(int duration)
                                                                                                                                                                                                                                                                                                                                                                                                        for (cc=0; cc<3; cc++) {
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   for (cc=0; cc<3; cc++) {
                                                                                                                                                                                     short (*tmp[3])[64];
                                                                                     int i, j, k, s, cc;
                                                                                                                                                      double alpha;
                                                                                                                                                                                                                                                                                                                                                                                                                                       if (cc==0)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      initbits();
                                                                                                                                                                                                                  ld = &S1;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              ld = &S2;
                                                                                                                                                                                                                                                 initbits();
                                                                                                                         int blks;
Appendix
                                                                                                                                                                                                                                                                                  2
                                                                                                                                                                                                                                                                                                                                                                                                                                        2
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             20
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      23
```

memcpy(auxDCT[cc], tmpDCT[cc], blks \* sizeof(short [64]));

blks = (chrom\_width\*chrom\_height)>>6;

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blks = (coded\_picture\_width\*coded\_picture\_height)>>6;

if (cc==0)

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_	<u>:</u>	nam v	A incuide for detecting inoving video objects in a compressed digital
7		bitstres	bitstream which represents a sequence of fields or frames of video
6		inform	information for one or more previously captured scenes of video,
4		compri	comprising the steps of:
2		æj	analyzing said compressed bitstream to locate scene cuts therein,
9			thereby determining at least one sequence of fields or frames of
7			video information which represents a single video scene;
∞		غد	estimating one or more operating parameters for a camera which
6			initially captured said video scene by analyzing a portion of said
0			compressed bitstream which corresponds to said video scene; and
_		ن	detecting one or more moving video objects represented in said
7			compressed bitstream by applying global motion compensation with
			said estimated operating parameters.

- The method of claim 1, further comprising the step of extracting visual features of said one or more detected moving video objects from said
  - compressed bitstream.
- The method of claim 1, wherein said compressed bitstream comprises a bitstream compressed in accordance with the MPEG video standard.
- The method of claim 1, wherein said analyzing step further comprises the steps of:
- parsing said compressed bitstream into blocks of video information
- and associated motion vector information for each field or frame of fields or frames of video information representative of said single video information which comprises the determined sequence of

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<b>00</b>	ض	performing inverse motion compensation on each of said parsed
6		blocks of video information to derive discrete cosign transform
0	i	coefficients for each of said parsed blocks of video information;
=	ن	counting said motion vector information associated with each of
12		said parsed blocks of video information; and
13	ę.	Determining from said counted motion vector information and sai
14		discrete cosign transform coefficient information whether one of
15		said scene cuts has occurred.

- information representative of said single scene, and wherein said estimating The method of claim 1, wherein said analyzing step comprises parsing said step comprises the step of estimating any zoom and any pan of said camera by determining a multi-parameter transform model applied to said parsed motion vector information for each field or frame of video information compressed bitstream into blocks of video information and associated which comprises the determined sequence of fields or frames of video notion vector information. Ś
- The method of claim 5, wherein said estimating step comprises the steps of:
  - computing each parameter for a multi-parameter affine transform which represents a transformation from a current frame of video information to a previous frame of video; and
- determine global motion information representative of said zoom computing said multi-parameter affine transform to thereby and pan of said camera. نم
- said global motion information and on one or more of said motion vectors The method of claim 6, wherein said detecting step comprises computing local object motion for said one or more moving video objects based on which correspond to said one or more moving video objects.

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_	œ	The method of claim 7, further comprising the steps of:
2		a. determining whether said local object motion is greater than a
6		predetermined threshold;
4		<ul> <li>applying morphological operations to said determined local object</li> </ul>
S		motion values to eliminate any erroneously sensed moving objects;
9		pur
7		c. determining border points of said detected moving objects to
∞		thereby locate a bounding box for said detected moving object.
_	6.	An apparatus for detecting moving video objects in a compressed digital
7		bitstream which represents a sequence of fields or frames of video
3		information for one or more previously captured scenes of video,
4		comprising:
2		<ul> <li>a. means for analyzing said compressed bitstream to locate scene cuts</li> </ul>
9		therein and to determine at least one sequence of fields or frames of
7		video information which represents a single video scene;
<b>∞</b>		<ul> <li>b. means, coupled to said analyzing means, for estimating one or more</li> </ul>
6		operating parameters for a camera which initially viewed said video
0		scene by analyzing a portion of said compressed bitstream which
_		corresponds to said video scene; and
7		c. means, coupled to said estimating means, for detecting one or more
3		moving video objects represented in said compressed bitstream by
4		applying global motion compensation with said estimated operating
S		parameters.
	10.	The apparatus of claim 9, further comprising means, coupled to said
7		detecting means, for extracting visual features of said one or more detected
m		moving video objects from said compressed bitstream.

-	=	The a	The apparatus of claim 9, wherein said compressed bitstream comprises a
7		bitstre	bitstream compressed in accordance with the MPEG video standard, and
٣		where	wherein said analyzing means further comprises:
4		તાં	parsing means for receiving and parsing said compressed bitstream
5			into blocks of video information and associated motion vector
9			information for each field or frame of video information which
7			comprises the determined sequence of fields or frames of video
00			information representative of said single scene;
6		ِ <b>ئے</b>	means, coupled to said parsing means, for performing inverse
10			motion compensation on each of said parsed blocks of video
Ξ			information to derive discrete cosign transform coefficients for eac
12			of said parsed blocks of video information;
13		ပ	counting means, coupled to said inverse motion compensation
14			means, for counting said motion vector information associated with
15			each of said parsed blocks of vide information; and
16		ė	determining means, coupled to said counting mens, for determining
17	,		from said counted motion vector information and said discrete
18			cosign transform coefficient information whether one of said scene
19			cuts has occurred.

and wherein said estimating means further comprises means for estimating

any zoom and any pan of said camera by determining a multi-parameter

transform model applied to said parsed motion vector information.

frame of video information which comprises the determined sequence of fields or frames of video information representative of said single scene,

information and associated motion vector information for each field or means for parsing said compressed bitstream into blocks of video

The apparatus of claim 9, wherein said analyzing means further comprises

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_	13.	I ne at	the apparatus of claim 12, wherein said estimating means further
~		comprises:	ises:
_		esi	means for computing each parameter for a multi-parameter affine
-+			transform which represents a transformation from a current frame of
			video information to a previous frame of video; and
S		فہ	means, coupled to said transform parameter computing means, for
			computing said multi-parameter affine transform to thereby
20			determine global motion information representative of said zoom
•			and pan of said camera.

- The apparatus of claim 12, wherein said detecting means further comprises of said motion vectors which correspond to said one or more moving video video objects based on said global motion information and on one or more means for computing local object motion for said one or more moving 4
- comparison means, coupled to said local object motion computing means, for determining whether said local object motion is greater moving objects to thereby locate a bounding box for said detected means, for determined local object motion values to eliminate any border point determination means, coupled to said morphological operation means, for determining border points of said detected morphological operation means, coupled to said comparison erroneously sensed moving objects; and The apparatus of claim 14, further comprising: than a predetermined threshold; moving object. 15. 2

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A method for dissolving an incoming scene of video information which

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2	сошы	comprises a sequence of fields or frame of compressed video information
2	and ar	and an outgoing scene of video information which comprises a sequence of
4	fields	fields or frame of compressed video information, comprising the steps of:
s	æj	applying DCT domain motion inverse compensation to obtain DCT
9		coefficients for all blocks of video information which make up a las
7		frame of said outgoing video scene;
∞	غہ	applying DCT domain inverse motion compensation to obtain the
6		DCT coefficients for all blocks of video information which make up
10		the first frame of said incoming video scene; and
	ပ	creating a first frame in a dissolve region from said DCT
12		coefficients of said last outgoing frame and said first incoming
13		frame.

- The method of claim 16, further comprising the step of choosing an initial 17.
- coefficients of said last outgoing frame and said first incoming creating a second frame in said dissolve region from said DCT frame using said incremented weighing function value. The method of claim 17, further comprising the steps of incrementing said weighting function value; and value for a weighing function prior to step (c). <u>.</u>ë
- A method for masking a region of a compressed frame of digital video determining whether said frame to be masked is intra-coded, predictive-coded or bi-directionally predictive-coded; information, comprising the steps of: if said frame is intra-coded: ز. 19.
- extracting DCT coefficients for all blocks within said frame; examining block, to determine where in said frame said block is located;

		iii. setting said DCT coefficients for said block to zero if said	1	22.	The method of claim 20, further comprisin
		block is outside said mask region;	2		frame into an intra-coded frame if said fran
		iv. applying a DCT cropping algorithm to said DCT	3		directionally predictive-coded frame.
		coefficients if said block is on the boundary of said mask			
		region; and		23.	A system for editing compressed video inf
		v. repeating steps (b)(ii) - (b)(iv) for each block in said frame;	2		network, comprising:
	ပ	If said frame is predictive-coded or bi-directionally predictive-	3		a. a client computer;
		coded:	4		b. a network link, coupled to said clie
		i. examining motion vectors associated with block, to	S		client computer to search for and le
		determine whether they point to blocks outside or on said	9		information on said distributed net
		mask region;	7		c. means for editing a compressed bit
		ii. reencoding said block if a motion vector points to blocks	∞		said distributed network.
		outside or on said mask region; and			
		iii. repeating steps (c)(i) - (c)(ii) for all blocks in said frame.	-	24.	The system of claim 21, wherein said editi
			2		dissolving an incoming scene of video infe
70.	A me	A method for generating a reduced speed sequence of frames of video	9		sequence of fields or frame of compressed
	infor	information from a sequence of frames of compressed video information,	4		outgoing scene of video information which
	сошр	comprising the steps of:	S		frame of compressed video information, sa
	æj	selecting a frame of compressed video information to be repeated;	9		a. outgoing motion compensation me
	ب	determining whether said frame to be repeated is intra-coded,	7		motion compensation to a last fram
		predictive-coded or bi-directionally predictive-coded;	00		obtain DCT coefficients for all blo
	ပ	converting said frame into an intra-coded frame if said frame is a	6		make up said last frame of said out
		predictive-coded or bi-directionally predictive-coded frame;	10		b. incoming motion compensation me
	Ģ	creating duplicate predictive-coded frames; and			motion compensation to a first fran
	ပ်	arranging said determined frame and said duplicate predictive-coded	12		to obtain the DCT coefficients for
		frames into a sequence of compressed frames of video information.	13		which make up said first frame of s
			14		c. dissolve region creating means, co
21.	The n	The method of claim 20, wherein said reduced speed sequence of frames	15		compensation means and to said or
-	gener	generates a frozen frame effect.	16		means, for creating a first frame ir
			ŗ		A maintain and bing to see the

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7		frame	frame into an intra-coded frame if said frame is a predictive-coded or bi-
3		directi	directionally predictive-coded frame.
-	23.	A syst	system for editing compressed video information over a distributed
7		netwo	network, comprising:
٣		તાં	a client computer;
4		ف	a network link, coupled to said client computer, for permitting said
S			client computer to search for and locate compressed video
9			information on said distributed network; and
7		ပ	means for editing a compressed bitstream of video information ow
œ			said distributed network.
-	24.	The sy	The system of claim 21, wherein said editing means includes means for
7		dissol	dissolving an incoming scene of video information which includes a
٣		sedne	sequence of fields or frame of compressed video information and an
4		ontgo	outgoing scene of video information which includes a sequence of fields
8		frame	frame of compressed video information, said dissolving means comprising
9		æi	outgoing motion compensation means for applying DCT domain
7			motion compensation to a last frame of said outgoing video scene
00			obtain DCT coefficients for all blocks of video information which
٥			make up said last frame of said outgoing video scene;
9		Þ.	incoming motion compensation means, for applying DCT domain
Ξ			motion compensation to a first frame of said incoming video scene
12			to obtain the DCT coefficients for all blocks of video information
13			which make up said first frame of said incoming video scene; and
4		ပ	dissolve region creating means, coupled to said incoming motion
15			compensation means and to said outgoing motion compensation
16			means, for creating a first frame in a dissolve region from said DC
17			coefficients of said last outgoing frame and said first incoming
38			frame.

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The	system o	The system of claim 21, wherein said editing means includes means for	7	
mask	ing a reg	masking a region of a compressed frame of digital video information, said	3	
mask	ing mea	masking means comprising:	4	
æj	means	means for determining whether said frame to be masked is intra-	8	
	coded	coded, predictive-coded or bi-directionally predictive-coded;	9	
ف	mean	means for processing intra-coded frames including:	7	
	:	means for receiving DCT coefficients and for extracting	∞	
		DCT coefficients for all blocks within said frame;	٥	
	: <b>=</b> i	means, coupled to said receiving means, for examining	10	
		blocks of compressed video information in said frame to	11	
		determine where in said frame said block is located;	12	
	ij	means, coupled to said examining means, for setting said	13	
		DCT coefficients for said block to zero if said block is	4	
		outside said mask region; and		
	.≥.	means, coupled to said setting means, for applying a DCT	-	7
		translation algorithm to said DCT coefficients if said block	2	
		is on the boundary of said mask region; and	m	
ပ	mean	means for processing predictive-coded and bi-directionally	4	
	predic	predictive-coded frames, including:	8	
	:	means for receiving and examining motion vectors	9	
		associated with blocks of video information to determine	7	
		whether they point to blocks outside or on said mask region;	∞	
		and	6	
	∷≓	means, coupled to said receiving means, for reencoding said	10	
		block if a motion vector points to blocks outside or on said	11	
		mask region.	12	
			13	

The system of claim 21, wherein said editing means includes means 9

generating a reduced speed sequence of frames of video information from a frame arranging means, coupled to said frame generating means, for frame generating means, coupled to said computational means and to said converting means, for creating duplicate predictive-coded determining whether said frame to be repeated is intra-coded, computational means, coupled to said selection means, for sequence of frames of compressed video information, comprising: selection means for selecting a frame of compressed video predictive-coded or bi-directionally predictive-coded; information to be repeated; ئے ij

arranging said determined frame and said duplicate predictive-coded frames into a sequence of compressed frames of video information. A method for converting a full resolution compressed domain bitstream 7.

determining whether said examined frame is intra-coded, predictiveexamining a frame of compressed video information from said full into a reduced resolution compressed bitstream, comprising the steps of: coded or bi-directionally predictive-coded; resolution bitstream;

extracting DCT DC coefficients for said determined frame if said determined frame is intra-coded

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to extract DCT DC coefficients if said frame is predictive-coded or applying DCT domain inverse motion compensation to said frame bi-directionally predictive-coded; and

converting said extracted DCT DC coefficients into DCT DC coefficients for a reduced size intra-coded frame of video.

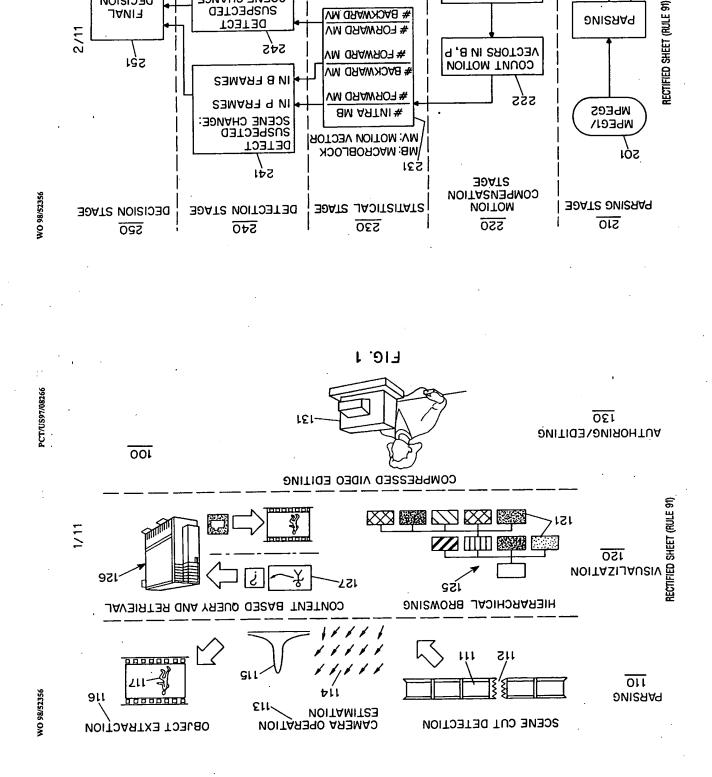


FIG. 2

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VARIANCE

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COMPENSATION P NI DC TOC 90 B RO

INVERSE MOTION

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DETECT DISSOLVE

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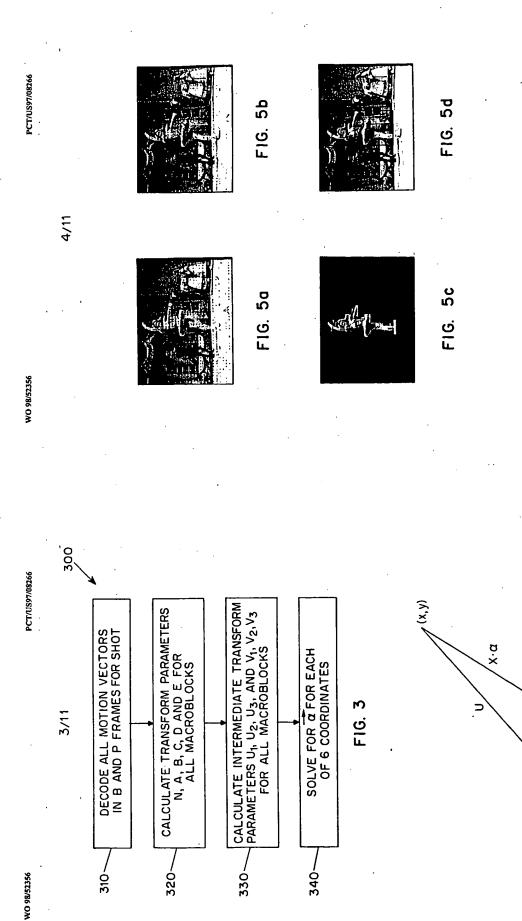
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LIST

**SCENE** 

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RECTIFIED SHEET (RULE 91)

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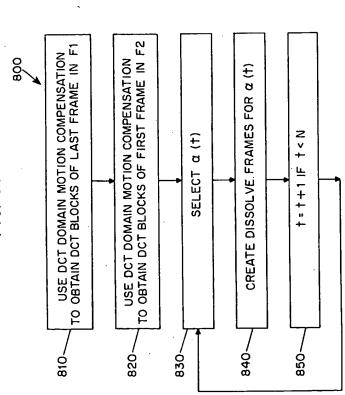
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RE-EUCODED FRAMES RE-EUCODED FRAMES **MA3972T18** 988188988. 988**1>98**188988. 188**91** NEM FRAMES IN ITALIC REQUIRE FRAME TYPE CONVERSION RECTIFIED SHEET (RULE 91) NEW GOP 6/11 .188988988 988188988. 988**9**\$\$889881 **NIDEO S** <del>06</del>2 SEGMENT 2 057 VIDEO 1 ... PBBPB 8 8 PBBI. .1889881 88188188 SEGMENT 1 012

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RECTIPIED SMEET (RULE 91)

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N=N+1 IF'N = M

N=N+1 IF N < M

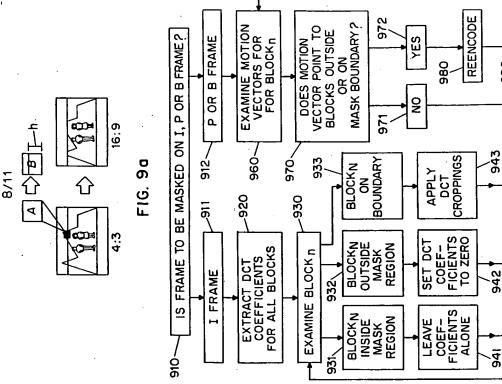
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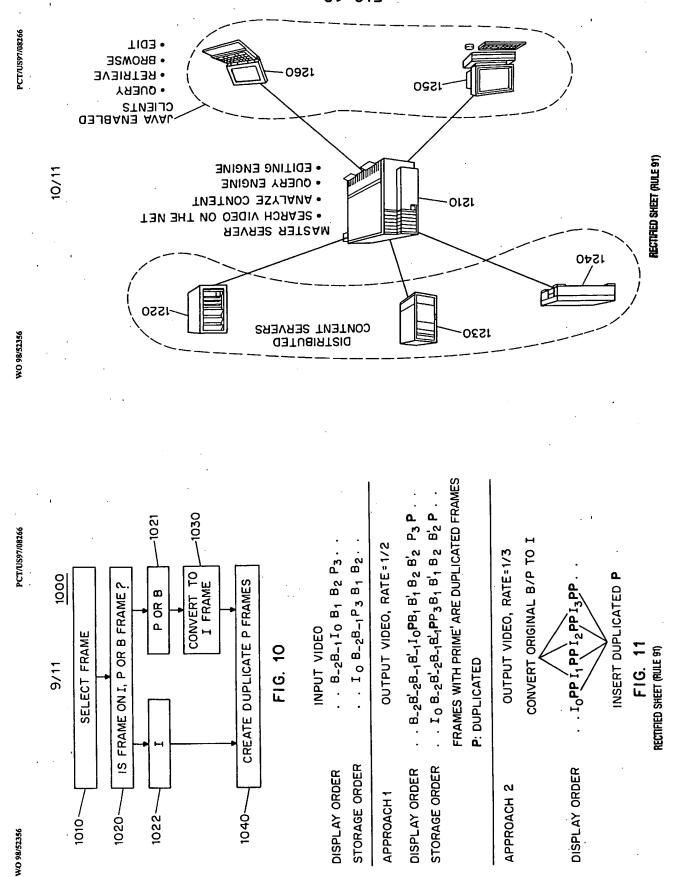
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FIG.

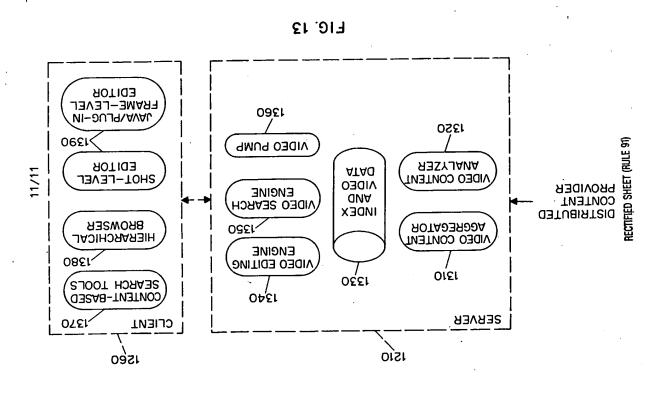
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INTERNATIONAL SEARCH REPORT



Relevant to claim No. Documentation searched other than minimum documentation to the extent that such documents are included in the fields scarched Electronic data base consulted during the international scarch (name of data base and, where practicable, scarch terms used) International application No. PCT/US97/08266 16-27 Date of mailing of the international search report 16-27 1-27 1-15 1-27 US, 5,606,655 A (ARMAN et al) 25 February 1997, column 6, lines 24-68; column 7, lines 20-68; column 8, lines 8-68; column 9, lines 29-68. US, 5,353,391 A (COHEN et al) 04 October 1994, column 16, lines 30-68; column 29, lines 10-60. US, 5,461,679 A (NORMILE et al) 24 October 1995, column 13, lines 24-67; column 14, lines 28-67; column 16, lines 20-45. (703) 305-4700 Citation of document, with indication, where appropriate, of the relevant passages 280CT 1997 :342/416, 415, 384, 411, 699 to International Patent Classification (IPC) or to both national classification and IPC See patent family Иовиму Р. СНІМ US, 5,262,856 A (LIPPMAN et al) 16 November 1993 APS: scene cut, scene change, fading, freeze frame, dissolve, masking, MPEG. US, 5,408,274 A (CHANG et al) 18 April 1995. U.S. : 348/384, 385, 404, 405, 409, 411, 415, 416, 699, 700; 352/129 documents are listed in the continuation of Box C. DOCUMENTS CONSIDERED TO BE RELEVANT Date of the actual completion of the international search CLASSIFICATION OF SUBJECT MATTER Dox Washington, D.C. 20231 Fectimile No. (702) 305-3230 Form PCT/ASA/210 (second sheet)(July 1992)\* Name and mailing address of the ISA/US Commissioner of Patents and Trademarks Box PCT Washington, D.C. 20211 FIELDS SEARCHED 21 AUGUST 1997 Category

INTERNATIONAL SEARCH REPORT

International application No. PCT/US97/08266

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C (Continu	then) DOCUMENTS CONSIDERED TO BE RELEVANT	
Category*	Citation of document, with indication, where appropriate, of the relevant pattages	Relevant to claim No.
∢	US, 5,204,706 A (SAITO) 20 April 1993.	1-15
<	US, 5,191,645 A (CARLUCCI et al) 02 March 1993.	1-15
		<u></u>
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